# Shibaura Machine

# INDUSTRIAL ROBOTS

# PRODUCT LINEUP



# Wide-ranging and various industrial robots contribute to automation, labor saving and increased efficiency.



The close integration and synergy of mechanical engineering and electronic control technologies gave birth to Shibaura Machine's industrial robots.

All the experience in design and production technologies acquired over its long history as a machine builder is reflected in its high-class machines and the controllers that drive them.

A line-up of three categories of robots each ranging from compact to large has been established.

They help to provide the optimized industrial automation solutions, resulting in increased productivity, and labor and cost reduction.



# New Robot Line SCARA Robot THE Series

# THE600 / THE400

New standard in SCARA robot High performance to meet automation needs

Accurate movement trajectory, high-speed operation and high load capacity are achieved at the same time

High-performance, high rigidity SCARA robots with a thoroughly redesigned mechanism and control functions

 Suitable for the assembly and inspection process of electronics equipment and automobile components where precision is crucial

THE400 and THE600 to meet the automation needs of faster cycle time.

Suitable for the assembly and inspection process of electronics equipment and automobile components where precision is crucial.

The THE600 is a new addition to the THE series. Combines with the newly developed TS5000 controller with its cutting-edge control performance and network functionalities and the newly developed TP5000 teach pendant, it contributes to improving efficiency, quality and the early return on investment in automation facilities.



THE400 ceiling mount (optional)



# SCARA Robot

## **THE600**

Arm length 600 mm, standard cycle time is at 0.3 seconds level (at 2 kg load), allowable moment of inertia 0.25 (kgm²); fast motions and heavy load are achieved at the same time.

Key specilic	ations	THE6UU		
Arm length		600 (325 + 275) mm		
Maximum lo	ad mass	12 kg		
Standard cy	cle time	0.31 sec		
Allowable me	oment of inertia	0.25 kgm <sup>2</sup>		
Positioning X-Y		±0.01 mm		
repeatability Z (axis 3)		±0.01 mm		
C (axis 4, rotation)		±0.005 deg		
Controller		TS5000		



## SCARA Robot **THE400**

Arm length 400 mm, standard cycle time is at 0.39 seconds (at 2 kg load), allowable moment of inertia 0.06 (kgm²); accurate movement trajectory, fast motions and heavy load are achieved at the same time. THE400 is a high rigidity robot with thoroughly redesigned mechanism and control functions.

Key specifica	ations	THE400	
Arm length		400 (225+175) mm	
Maximum lo	ad mass	5 kg	
Standard cy	cle time	0.39 sec	
Allowable mo	oment of inertia	0.06 kgm <sup>2</sup>	
Positioning	X-Y	±0.01 mm	
repeatability Z (axis 3)		±0.01 mm	
	C (axis 4, rotation)	±0.007 deg	

TSL3000, TSL3000E

#### TS5000 Robot controller



Improvement in synchronized control and tracking precision by better servo performances. Improved communication performances, and IoT-ready fast data communication.

Faster control cycle (three times faster than the previous model) results in improved synchronized control and tracking precision. Enhanced CPU and Ethernet facilitate fast transmission of internal data.

#### Teach pendant

# **TP5000**

Improved operability

Controller



With 7-inch, widescreen color touch-sensitive panel, intuitive operation is realized. In the larger display area, programs and position data can be checked in one glance. With split-screen display, two sets of data can be displayed side-by-side, for example the current position display and program

#### Designed for ease of handling and operation

Fast boot-up, ready in 30 seconds from power on. Multiple languages switchable in the settings, (Japanese, English, Chinese and Korean planned). AUTO/MANUAL master mode switching with the key switch on the teach pendant.





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# **New Generation Robot Programming Assist Tool**

**TSAssist** 

Powerful assistance to all phases of automation 5 facilities, from planning, installation to enhancement



# Applicable robots: SCARA Robots, Vertical Articulated Robots







- SimulationAccurate simulation with interference check, locus display, timer (cycle time measurement)
- Placing simple workpieces and model shapes
- Loading 3D CAD data, saving 3D simulation to a video file
- Multi-angle view

#### Highly Functional Program Editor



- Language input support (keyword suggestions)
- Outline display, Split display
- Point data (taught position information) editor with, sort, search, filter functions
- In 3D Editor Mode, the robot can be guided by dragging the mouse or clicking on the surfaces of the object models.

#### Key Features

#### Easy Operation

Easy-to-understand, intuitive screen design, ribbon interface, windowdock function for customize-able operator panels. Beginners will find it easy to understand and can quickly learn robot programing skills. For experienced robot users, TSAssist helps making robot programs efficiently by customization.

#### Solution Function

A simulation environment for a production line including multiple robots can be archived into a folder.

#### Multiple Language Support

Switch-able between English, Chinese (Traditional and Simplified) and Japanese. TSAssist allows smooth collaboration with overseas installations.

Please visit our website for details.



# Robot Vision Recognition Package

# TSVision3D

# Easy Introduction of **Bin-picking Automation System**



GiaE

## Applicable robots: Vertical Articulated Robots



SVision3D

PC software

### POINT 1 Package consists of stereo camera, PC software and LED lighting

- Real-time and highly accurate 3D measurement by stereo camera
- Random pattern projection by high luminosity LED
- High speed (30 fps) and high accuracy image processing
- With larger depth, more workpieces can be included per one box

### POINT 2 Software functions

- Easy model registration
- Easy calibration (registration of robot and camera coordinates)
- Box position registration and interference avoidance function
- Checking for arm working envelope

Please visit our website for details.



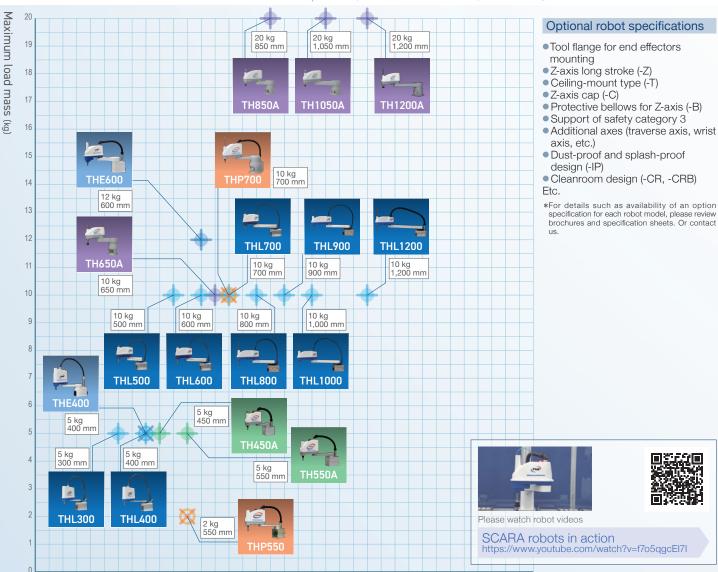
Please watch robot videos https://www.youtube.com/watch?reload=9&v=DK9rtdZRat0

System Configurations

Stereovision system

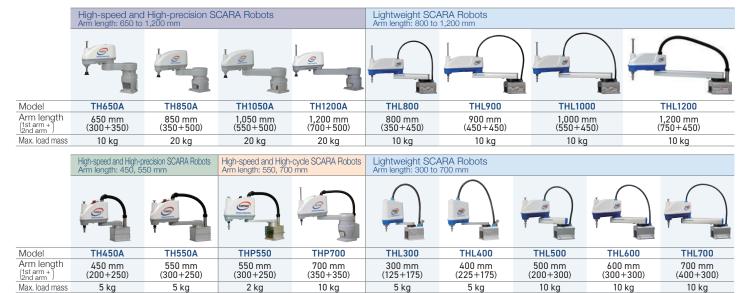






Arm length (mm)

1.600 1.700 1.800



1.100

1.300

1.400

1.500

Max. load mass	5 kg	5 kg	2 kg	9	10 kg		5 kg
Controller		6	- 1				<b>0:</b> :
Model	TS3000	TS31	00	TS	L3000		TSL3000E
Robot models	TH450A TH550A THP500		TH1200A THP700	THI	_400	THL600 THL700 THL800	THL1000

#### Main controller options

- Additional axes I/O signal polarity
- N-type
   P-type

I/O cables

- Position date latch function
   Separated operation panel Smooth (constant speed • CE marked and KCs marked control) function
- Additional I/O signals Field network connectivity Conveyor synchronization
  - PROFIBUS DeviceNet CC-Link Ethernet/IP • EtherCAT • PROFINET



100

300

400

500

600

800

900



Maximum load mass (kg.)

# Vertical Articulated Robots | More degrees of freedom suitable for assembly and transfer maneuvers

Optional robot specifications TVM series 20 kg 900 mm Hollow 3rd arm 18 I/O panel with built-in three-way solenoid valves 17 I/O panel Ethernet port • Cleanroom design (ISO class 3) 16 Ceiling mount TV series 15 Dust and drip proof (IP65) Cleanroom design (ISO class 3) Ceiling mount 13 I/O panel with built-in three-way solenoid valves 12 Dust and water proof (IP67) \* 10 kg 1,500 mm \* Only for wrist of TV1000H 11 TV1000H TVL series I/O panel with built-in three-way solenoid valves Dust and drip proof (IP65) Cleanroom design (ISO class 3) \*For details such as availability of an option specification for each robot model, please review brochures and specification sheets. Or contact TV800 TV1000 5 kg 800 mm 5 kg 1,000 mm TVI 500 3 kg 500 mm TVM1200 Please watch robot videos **TVL700** Vertical articulated robots in action 4 kg 700 mm https://www.youtube.com/watch?v=TkO5Zy6ZGYE 0 300 400 500 600 800 900 1.000 1,100 1,200 1.300 1,400 1.500 1,600 1,700 1,800

Arm length (mm)



	TVL series	
Model	TVL500	TVL700
Arm length	500 mm	700 mm
Max. load mass	3 kg (Downward: 5 kg)	4 kg (Downward: 5 kg)

Controller	9.			.8.
Model	TSL3100	TSL3100E	TS3100	TSL3200E
Robot models	TVL TVL	500 700	TV800 TV1000 TV1000H	TVM900 TVM1200 TVM1500

#### Main controller options

Additional I/O signals I/O cables

Field network connectivity • PROFIBUS DeviceNet CC-I ink

EtherCAT

PROFINET

Ethernet/IP

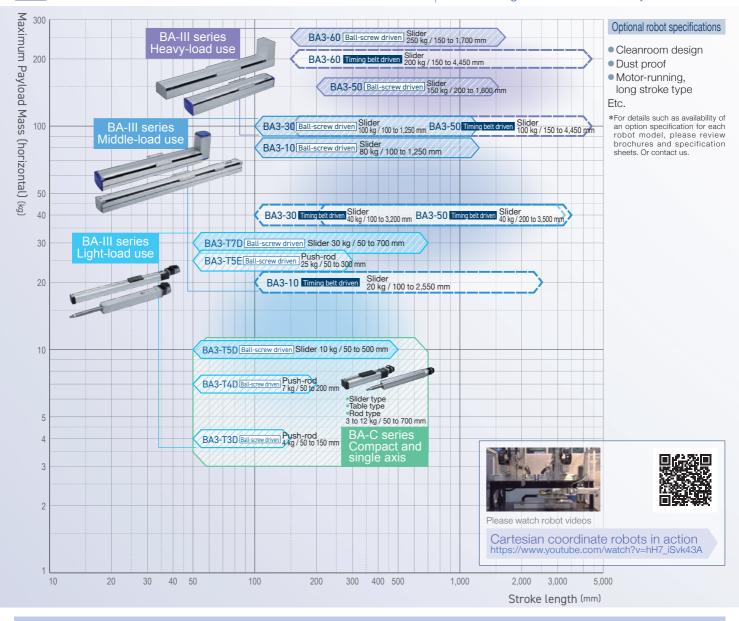


Additional axes



# Cartesian Coordinate Robots

Reliable and agile Cartesian robots with flexible and varied configurations to meet factory floor needs



#### Typical Examples of Cartesian Axes Specifications



Number of axes 2 axes		2 axes	
Coordinate type	X-Y combination	X-Z combination	



Number of axes	2 axes	2 axes	
Coordinate type	Z-Y combination	Y-Z combination	



4 axes

Coordinate type	X-Y-Z com	X-Y-Z combination		X-Y-Z-R combination		
Controller		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	E .			

3 axes

Model	CA25-M10	CA25-M40 CA25-M80	CA25-S10	CA25-S40 CA25-S80
Type	Master unit	Master unit	Slave unit	Slave unit

#### Main controller options

Number of axes

Additional I/O signals

 Field network connectivity CC-Link
 Ethernet/IP DeviceNet





# Robot selection guidelines

In order to select a robot model please consider the following factors:

Mass and centre of gravity offset values of the workpiece and end of arm effector combined

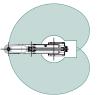
Environmental requirements of installation site

Environment types: general, cleanroom, dust and splash proof, etc.

Area coverage requirement and installation configurations

Please review the external dimension drawing (CAD file) of each model for the working envelope (area coverage).

For example: Standard floor-mounted configuration, optional ceiling-mount configuration, etc. For example: For a SCARA robot, whether vertical (Z) long-stroke option is required.



An example SCARA robot working envelope

The robot motion patterns and the time

requirement (cycle time) review

Cable length requirements, the distance between the robot and the controller

Please refer to the specification table of each model for standard cable lengths.

For example: Optional cable lengths are available.

For example: Optional movable cable is available.

Controller option requirements

Please refer to the specification table of each model for available controller options.

For example: additional I/O signals are required.

For example: optional field network connectivity is required.



Teach pendant (optional)

Please select according to the robot type.

For SCARA and vertical articulated robots







TP3000 (High-end model)

TPH-4C

For Cartesian robot

PC software

Please select according to the robot type.

**TSAssist** 

Programming assistance software for SCARA and vertical articulated robots

**TCPRGOS** 

Programming assistance software for TCmini (built-in PLC). SCARA and vertical articulated robots

Programming assistance software for Cartesian robots

\*This document presents an overview of our robot product lineup. For full details, such as specification data, external dimension CAD files, please refer to the brochure for each model and our website. And, please contact our sales representatives with any questions you may have.

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